

國科會社會科學研究中心學術研習營

# 生產隨機邊界模型介紹

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# Basic

- 古典生產理論認為，平均而言，生產者皆能將生產技術充分發揮。
- 生產邊界理論則認為，由於疏忽、經驗不足、管理不當等因素，生產技術常常無法被充分發揮，導致系統性 (systematic) 的「無效率」的存在。

## 如何定義與衡量無效率？

- 以生產函數為著眼點
  - ◇ 要素數量為外生給定，產量為內生；
  - ◇ 可能引起技術無效率（較簡單）；
- 以成本函數為著眼點
  - ◇ 給定產量及要素價格；要素使用量為內生；
  - ◇ 可能引起技術無效率及配置無效率（較複雜）；
- 以利潤函數為著眼點
  - ◇ 產量與要素使用量皆為內生；
  - ◇ 可能引起技術無效率 + 配置無效率（較複雜）。

## 生產函數

- $y^* = f(x_1, x_2, \dots, x_n; \beta) \equiv f(\mathbf{X}; \beta)$

- ◇  $\mathbf{X}$ : 生產投入

- ◇  $f(\dots)$ :「生產技術」

- ★ 例:1麵包 = 0.5個蛋 + 0.5斤麵粉;1蛋糕=2個蛋+1斤麵粉;

- ◇  $y^* = f(\mathbf{X}; \beta)$  表示當「充分發揮 生產技術」時的產出與投入的關係。即: 給定投入  $\mathbf{X}$  與生產技術  $f(\cdot)$ 時, 所能得到的「最大」產出.

## 例子:2項投入;3D

$y = f(x_1, x_2; \beta)$ 描繪的是圓椎體的「表面」。

- 裡面的點?!

## 例子:2項投入; 縱切面 (給定 $x_2$ )

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- 古典:(平均而言) 生產活動/行爲皆發生在圖1圓椎的表面, 或圖2的 最大生產可能線。
- 生產邊界理論: 生產活動有可能在圖1的圓椎之「內」, 或圖2的 生產可能線之下。亦即, 存在「技術無效率」(technical inefficiency; TI), 使得產量無法達到最大。



## 兩種角度評估技術無效率

- 用了太多的投入!生產 $y_b$ 卻用了 $x_1^1$ ; if fully efficient, need only  $x_1^2 < x_1^1$ .  $\implies$  input-oriented (IO) measure of technical inefficiency.
- 得到太少的產出!使用 $x_1$ 竟只得到 $y_b$ !If fully efficient, should get  $y_B > y_b$ .  $\implies$  output-oriented (OO) measure of technical inefficiency.

## IO technical inefficiency

$$y = f(x \cdot e^{-\eta}), \eta \geq 0.$$

- Note:  $0 < e^{\theta} < 1$  if  $\theta < 0$ ;  $e^{\theta} = 1$  if  $\theta = 0$ ;  $e^{\theta} > 1$  if  $\theta > 0$ .
  - ◇ Therefore,  $0 < e^{-\eta} \leq 1$  given  $\eta \geq 0$ .
- $x$ : 「觀察到」的使用投入 (太浪費);  $y$ : 「觀察到」的產出;
- $x e^{-\eta}$ : 在給定的技術水準下 (i.e.,  $f(\cdot)$ ), 使用較少的投入, 就可得到相同的產出。

## OO technical inefficiency (較常用)

- $y = y^* \cdot e^{-u}$ , where  $u \geq 0$  and  $y^* = f(x; \beta)$  (古典)

◇ therefore,

$$y = f(x; \beta) \cdot e^{-u}, u \geq 0, \quad (1)$$

$$\Rightarrow ye^u = f(x; \beta); \quad (2)$$

若 fully efficient, 使用相同的投入, 可得到比觀察到的更多的產出;

$$ye^u > y.$$

# OO technical inefficiency of a production function: more closely

$$y = f(x)e^{-u} = y^*e^{-u}, \quad u \geq 0; \quad e^{-u} = y/y^*; \quad -u = \ln(y/y^*) \quad \text{so}$$
$$u = \ln(y^*/y) = \ln((y + \Delta y)/y) = \ln(1 + \Delta y/y) \approx \Delta y/y.$$

## Measures of (In)Efficiency

- **efficiency score:**

$$y = f(x)e^{-u} = y^*e^{-u}, u \geq 0; \implies e^{-u} = y/y^*;$$

so  $e^{-u}$  measures the percent of potential output actually achieved; a measure of **technical efficiency**;

- **inefficiency score;**

$$-u = \ln(y/y^*),$$

$$u = \ln(y^*/y) = \ln((y + \Delta y)/y) = \ln(1 + \Delta y/y) \approx \Delta y/y;$$

so  $u$  measures the percent of output loss (when multiplied by 100) due to technical inefficiency.

## 估計模型之前...

- A crucial question: Do the samples share the same production technology?
  - ◇ The inefficiency is measured as the distance between the actual output and the optimal output.
  - ◇ Optimal output is measured conditional on the production technology; that is, the production technology is the same for all individuals.
  - ◇ If they do not share the same technology, the estimates of inefficiency is misleading.
- Bad examples: pooling China and US banks together; pooling firms from very different industries.

## 模型估計的目的

- 探討生產技術 (i.e., the  $\beta$  coefficients);
- 瞭解整體而言, 無效率是否嚴重 (i.e.,  $E(u_i)$  or  $E(e^{-u_i})$ );
- 分析導致無效率的因素 (i.e., what determines  $u_i$  );
- 比較生產者間的生產效率, 是否顯著不同 (i.e.,  $E(u_i)$  vs.  $E(u_j)$ );
- 將生產者的效率予以排序。

## 估計方法(OO;production frontier)

- Two goals:
  - ◇ obtain consistent coefficients ( $\beta$ ),
  - ◇ obtain *observation-specific* (in)efficiency index.

$$y_i = f(x_i; \beta)e^{-u_i}, \Rightarrow \ln y_i = \ln f(x_i; \beta) - u_i; \quad (3)$$

- 如何處理  $u_i$ ?
  - ◇ distribution free approach:
    - ★ COLS (corrected OLS);



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- ★ thick frontier approach; (will skip)
- ◇ parametric approach (based on distribution assumptions).
  - ★ half normal, truncated normal, etc.;

## Distribution-free approach: COLS

- Does not require (strict) distribution assumptions on  $u_i$ .
  - Estimate the model by OLS, and then shift the intercept to have the interpretation of a stochastic frontier.
- ◇ **step 1:** Want to estimate

$$y_i = \beta_0 + \beta_1 x_i - u_i, \quad u_i \geq 0, \quad (4)$$

but estimate instead the following by OLS

$$y_i = \beta_0^* + \beta_1^* x_i + v_i, \quad v_i \sim N(0, \sigma^2). \quad (5)$$

$\hat{\beta}_1^*$ : consistent estimate of  $\beta_1$ ;  $\hat{\beta}_0^*$ : *not* a consistent estimate of  $\beta_0$ .

- ◇ **step 2:** shift the regression line *upward* by the amount of  $\max\{\hat{v}_i\}$  (to bound all the data below) by adjusting the intercept:

$$\hat{v}_i - \max\{\hat{v}_i\} = \ln y_i - \underbrace{\left\{ \left[ \hat{\beta}_0^* + \max\{\hat{v}_i\} \right] + \tilde{\mathbf{x}}_i' \hat{\boldsymbol{\beta}}^* \right\}}_{\text{estimated frontier function}} \leq 0, \quad (6)$$

and that

$$\hat{u}_i \equiv -(\hat{v}_i - \max\{\hat{v}_i\}) \geq 0, \quad (7)$$

$\hat{u}_i$ : the estimated inefficiency index; technical efficiency of each observation:  $\widehat{TE}_i = \exp(-\hat{u}_i)$ .

## Comments on COLS

- Advantages:
  - ◇ easy to estimate; no special software needed;
- Disadvantages:
  - ◇ COLS is a shifted mean regression  $\implies$  difference between the efficient frontier producer and the mean producer only affects the intercept but not slope coefficients;
  - ◇ the frontier function is deterministic  $\implies$  (1) the randomness of the model comes entirely from inefficiency variation; (2) deviations from the estimated frontier are entirely attributed to inefficiency; (3) estimates of inefficiency would be sensitive to outliers.

## Parametric Approach: Setup

$$\ln y_i = \ln f(x_i; \beta) - u_i + v_i, \quad \text{where } v_i \sim N(0, \sigma^2), \quad (8)$$

- impose distributional assumption on  $u_i$ , and derive the likelihood function;
- obtain estimates of the coefficients by MLE;
- obtain *observation-specific* measure of technical inefficiency (tricky!).

## Parametric Approach: $u$ is Half-Normal

$$\ln y_i = \ln y_i^* - u_i, \quad (9)$$

$$\ln y_i^* = \mathbf{x}_i \boldsymbol{\beta} + v_i, \quad (\text{the efficient stochastic frontier}), \quad (10)$$

$$u_i \sim N^+(0, \sigma^2), \quad v_i \sim N(0, \sigma_v^2), \quad (11)$$

Or

$$\ln y_i = \mathbf{x}_i \boldsymbol{\beta} + \epsilon_i; \quad \epsilon_i = v_i - u_i, \quad (12)$$

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# **(half normal:) Density Plot**

## (half normal:) Log-Likelihood Function

$$L_i = -\ln(0.5) - \frac{1}{2} \ln(\sigma_v^2 + \sigma^2) + \ln \phi \left( \frac{\epsilon_i}{\sqrt{\sigma_v^2 + \sigma^2}} \right) + \ln \Phi \left( \frac{\mu_{*i}}{\sigma_*} \right), \quad (13)$$

where

$$\mu_{*i} = \frac{-\sigma^2 \epsilon_i}{\sigma_v^2 + \sigma^2}, \quad (14)$$

$$\sigma_*^2 = \frac{\sigma_v^2 \sigma^2}{\sigma_v^2 + \sigma^2}. \quad (15)$$



## (half normal:) Observation-Specific Measure of Inefficiency Index

- Recall that, for a production frontier model, inefficiency is measured by  $E(u_i)$  ( $= \Delta y/y$ ): percent of output loss.
- How?  $u \sim N^+(0, \sigma^2)$ , we obtain  $\hat{\sigma}^2$ , but then  $E(u)$  is a single value, not observation-specific?!
- Jondrow et al. (1982) solve the problem by using conditional expectation:
  - ◇  $E(u_i|\hat{\epsilon}_i) = E(u_i|y_i - X_i\hat{\beta})$ ,
  - ◇ since  $y_i - X_i\hat{\beta}$  is observation-specific, so would be  $E(u_i|\hat{\epsilon}_i)$ .

$$E(u_i|\epsilon_i) = \frac{\sigma_* \phi\left(\frac{\mu_{*i}}{\sigma_*}\right)}{\Phi\left(\frac{\mu_{*i}}{\sigma_*}\right)} + \mu_{*i}. \quad (16)$$

- the lower bound ( $L_i$ ) and the upper bound ( $U_i$ ) of a  $(1 - \alpha)100\%$  confidence interval:

$$L_i = \mu_{*i} + \Phi^{-1} \left\{ 1 - \left(1 - \frac{\alpha}{2}\right) \left[ 1 - \Phi\left(-\frac{\mu_{*i}}{\sigma_*}\right) \right] \right\} \sigma_*, \quad (17)$$

$$U_i = \mu_{*i} + \Phi^{-1} \left\{ 1 - \frac{\alpha}{2} \left[ 1 - \Phi\left(-\frac{\mu_{*i}}{\sigma_*}\right) \right] \right\} \sigma_*, \quad (18)$$

## (half normal:) Observation-Specific Measure of Efficiency Index (popular)

- Recall that, for a production frontier model, efficiency is measured by  $E(\exp(-u_i))$  ( $= y/y^*$ ): percent of potential output achieved. Close to 1, more efficient.
- Battese and Coelli (1988), following Jondrow et al. (1982), suggests a conditional expectation measure:

$$E[\exp(-u_i)|\epsilon_i] = \exp\left(-\mu_{*i} + \frac{1}{2}\sigma_*^2\right) \frac{\Phi\left(\frac{\mu_{*i}}{\sigma_*} - \sigma_*\right)}{\Phi\left(\frac{\mu_{*i}}{\sigma_*}\right)}. \quad (19)$$

- Confidence Intervals:

$$\mathcal{L}_i = \exp(-U_i), \quad (20)$$

$$\mathcal{U}_i = \exp(-L_i). \quad (21)$$

## (half-normal:) exogenous determinants

- Approach 1: After obtaining  $E(u_i|\epsilon_i)$ , do a Logit regression of  $E(u_i|\epsilon_i)$  on exogenous determinants  $\mathbf{z}_i$ . But this approach has serious problems:
  - ◇ the iid assumption of  $u_i$  is violated;
  - ◇ Wang and Schmidt (2002) show that the bias is significant.
- Approach 2: (Ford et al. 1993)  $u \sim N^+(0, \sigma^2 = g(\mathbf{Z}_i\delta)) \equiv N^+(0, \exp(\mathbf{Z}_i\delta))$ 
  - ◇ be careful of the interpretation:  $\delta$  is not marginal effect, although the sign is the same as the marginal effect's sign.

## **(half-normal:) test the one-sided error ( $u_i$ )**

- Since  $u_i \sim N^+(0, \sigma^2)$ , it amounts to test  $H_0 : \sigma^2 = 0$ . An LR test statistic of  $-2[L(H_0) - L(H_1)]$  was suggested, where  $L(H_0)$  and  $L(H_1)$  are log-likelihood values of the restricted model (OLS) and the unrestricted model (SF).
- Problem: The null ( $\sigma^2 = 0$ ) is on the boundary of the parameter space, and usual distributions do not apply.
- Coelli (1995) shows that the LR the test has a mix chi-square distribution, with critical values given in Kodde and Palm (1986).

## (half normal:) Comments

- Advantages:
  - ◇ easier to estimate (has only one parameter in  $u$ 's distribution);
- Disadvantages:
  - ◇ inflexible because has only one parameter to characterize the distribution;
  - ◇ the mode is at 0 (the full efficiency level).

## (half normal:) Remark 1

- Before you begin, it is always a good idea to check the skewness of the model's corresponding OLS residuals.
- (Schmidt and Lin, 1984) for a stochastic production frontier model, the OLS residuals should skew to the left (i.e., **negative** skewness) (recall  $v_i - u_i$ ).

- 

$$\sqrt{b_1} = \frac{m_3}{m_2 \sqrt{m_2}}, \quad (22)$$

$m_2$  and  $m_3$ : the second and the third sample moments of the OLS residuals.



## (half-normal:) Remark 2

- An often-reported but sometimes mis-used statistic:

$$\gamma = \frac{\sigma^2}{\sigma^2 + \sigma_v^2}. \quad (23)$$

- For half-normal model, the gamma may be used to test for the significance of the  $u_i$  term. (But could be used for truncated normal model; later.)
- It is often interpreted as the share of model variance coming from inefficiency. This is WRONG, because  $\text{var}(u) = (1 - 2/\pi)\sigma^2 \neq \sigma^2$ .

## Parametric Approach: $u$ is Truncated Normal

$$\ln y_i = \mathbf{x}_i \boldsymbol{\beta} + \epsilon_i, \quad (24)$$

$$\epsilon_i = v_i - u_i, \quad (25)$$

$$u_i \sim N^+(\mu, \sigma^2), \quad (26)$$

$$v_i \sim N(0, \sigma_v^2). \quad (27)$$

- The functional form is more flexible than the half-normal distribution.
- The mode of the distribution is not necessarily 0.

# **(truncated normal:) Density Plot**

Figure 1: Density Plot of Truncated-Normal Distributions

## (truncated normal:) log-likelihood function

$$L_i = -\frac{1}{2} \ln(\sigma_v^2 + \sigma^2) + \ln \phi \left( \frac{\mu + \epsilon_i}{\sqrt{\sigma_v^2 + \sigma^2}} \right) + \ln \Phi \left( \frac{\mu_{*i}}{\sigma_*} \right) - \ln \Phi \left( \frac{\mu}{\sigma} \right),$$

where

$$\mu_{*i} = \frac{\sigma_v^2 \mu - \sigma^2 \epsilon_i}{\sigma_v^2 + \sigma^2},$$
$$\sigma_*^2 = \frac{\sigma_v^2 \sigma^2}{\sigma_v^2 + \sigma^2}.$$

## (truncated normal:) Statistics

the observation-specific measure of inefficiency and the confidence intervals

- *skip; similar to those of the half-normal distribution; see book*

## (truncated normal:) Exogenous Determinants

- Given  $u_1 \sim N^+(\mu, \sigma^2)$ , how to account for the exogenous determinants of inefficiency?
- Battese and Coelli (1995):  $u_i \sim N^+(\mu = \mathbf{Z}_i\delta, \sigma^2)$ ;
- Problem: Why  $\mathbf{Z}_i$  enters through  $\mu$  but not  $\sigma^2$  (Wang, 2002)?

## (truncated normal:) Problem 1: Insufficient Parameterization

The moments of  $u$  are functions of both  $\mu$  and  $\sigma^2$ .

$$E(u) = f(\mu, \sigma) = \mu + \sigma \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right],$$

$$V(u) = g(\mu, \sigma) = \sigma^2 \left[ 1 - \frac{\mu}{\sigma} \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right] - \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right]^2 \right].$$

- There is no theoretical justification why exogenous factors  $z_{it}$  affect the moments of  $u$  through  $\mu$  but not  $\sigma$ .

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- Different elements in  $z_{it}$  may influence  $u$  through different channels.



## (truncated normal:) Problem 2: Efficiency Effects Are Necessarily Monotonic

- If only  $\mu$  is parameterized, the relationship between  $E(u)$  and elements of  $z_{it}$  are forced to be monotonic.
- Many economic relationships, however, are likely to be non-monotonic. For instances, the income tax rate and government revenues; the wage rate and labor supply; ages and labor efficiency; financial ratios (debt-asset ratio, interest-income ratio) and firm performances.
- **To sum up:** When  $z_{it}$  is only allowed in  $\mu$ , the exogenous factors' effects on  $u$  may not be fully accounted for, and their abilities to explain the model are compromised and restricted.

## (truncated normal:) The Improvement (Wang 2002)

- Make the model more flexible by allowing  $z_{it}$  to affect  $u$  through both  $\mu$  and  $\sigma^2$ .

$$\mu = \mathbf{Z}_i\delta, \quad \sigma^2 = \exp(\mathbf{Z}_i\gamma) \quad (28)$$

- This added flexibility has the benefit of accommodating non-monotonic efficiency effects of  $z_{it}$  on  $\mathbf{E}(u)$ . The marginal

effect of the  $k$ th element of  $z_{it}$  is:

$$\begin{aligned} \frac{\partial E(u_{it})}{\partial z[k]} = & \delta[k] \left[ 1 - \frac{\mu}{\sigma} \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right] - \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right]^2 \right] \\ & + \frac{\gamma[k]}{2} \left[ \left( \sigma + \mu \frac{\mu}{\sigma} \right) \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right] + \mu \left[ \frac{\phi\left(\frac{\mu}{\sigma}\right)}{\Phi\left(\frac{\mu}{\sigma}\right)} \right]^2 \right]. \end{aligned}$$

## (truncated normal:) An Empirical Example

- **Data** Outputs and inputs of Indian rice farmers. Unbalanced panel of 34 farmers, with a total number of observations equal to 271.
- **Variables** Same as Battese and Coelli (1995) and Coelli and Battese (1996).

$$y_{it}: \ln(Y_{it});$$

$$\mathbf{x}_{it}: \{\ln(Land_{it}), \ln(PI_{it}), \ln(Labor_{it}), \ln(Bullock_{it}), \\ \ln[\text{Max}(Cost_{it}, 1 - D_{it})], Year_{it}\};$$

$$\mathbf{z}_{it}: \{Age_{it}, Schooling_{it}, Year_{it}\},$$

# **(truncated normal:) Marginal Effects of Age on Inefficiency $E(u_{it})$**

Figure 2: (i): Battese and Coelli (1995); (ii): Wang (2002)

## (truncated normal:) Remark 1

- Recall the  $\gamma$  statistic:

$$\gamma = \frac{\sigma^2}{\sigma^2 + \sigma_v^2}. \quad (29)$$

- Is  $\sigma^2$  related to the variance of  $u_i$ ?
  - ◇  $u_i \sim N^+(\mu, \sigma^2)$ , so  $\text{var}(u_i)$  is a function of both  $\mu$  and  $\sigma^2$ .
- It conveys no useful information for a truncated normal model!  
So, do not use it!!

## Other distributional assumptions

- exponential distribution:
  - ◇ Has only 1 parameter, easy to estimate, very similar to the half-normal distribution.
- Gamma distribution (Greene):
  - ◇ Difficult to estimate (flat likelihood surface).

## Scaling Property Model (Wang and Schmidt 2002)

- An variant of the truncated normal model.
- $u_i \sim h(\mathbf{Z}_i, \delta) \times u^*$ :
  - ◇  $u^* \geq 0$ : *basic distribution*, common to all observation and is not depend on  $\mathbf{Z}_i$ . It can take any functional form (such as truncated normal)
  - ◇  $h(\mathbf{Z}_i, \delta) \geq 0$ : *scaling function*. For example,  $h(\cdot) = \exp(\mathbf{Z}_i\delta)$
- The model implies that the random variable  $u_i$  follows a common distribution  $u^*$ , but each is weighted by a different,



observation-specific scale of  $h(\cdot)$ .

- The *shape* of the distribution of  $u_i$  is the same for all firms. The scaling function  $h(\cdot)$  essentially stretches or shrinks the horizontal axis, so that the scale of the distribution of  $u_i$  changes but its underlying shape does not.
- Another advantage of this distribution:

$$\frac{\partial \ln u_i}{\partial z[k]} = \delta[k] \quad (30)$$

So, the coefficient has an intuitive interpretation (the effect on the change rate of inefficiency).

## Examples

- data: dairy farm production.
  - ◇ `ly`: output: the log of milk production,
  - ◇ `llabor`: labor hours,
  - ◇ `lfeed`: feed,
  - ◇ `lcattle`: number of cows,
  - ◇ `lland`: the farm's land size
  - ◇ `comp`: computer-related expenses to total expenses
- Software: by Hung-Jen Wang in Stata

以下內容將以電腦實際操作顯示。

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**(examples:) OLS**

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**(examples:) OLS residuals: graph**

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**(examples:) OLS residuals**

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**(examples:) COLS**

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# **(examples:) COLS Efficiency Score**



# **(examples:) Half-Normal Model**

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**(examples:) Half-Normal: graph**

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**(examples:) truncated-normal**

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**(examples:) truncated-normal: graph**

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**(examples:) truncated-normal: marginal effects**

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# Do different distributions matter?

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# **Do different distributions matter? Summary Statistics**

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# **Do different distributions matter? Correlation Coefficients**



## Do different distributions matter? Kendall's $\tau$

- ◇  $\tau$ :  $100(1 - \tau)/2$  gives the probability that a randomly chosen pair of observations have opposite rankings in the two series.